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## Highlights

- A wear prediction method of the piston/cylinder pair which can obtain the time-varying wear process of the piston/cylinder pair is established.
- The interaction between load-bearing and lubrication parameters and surface wear is taken into account.
- Both the experimental result and the simulation result show that the wear of two ends of the cylinder bore is relatively serious in the specific ranges of circumferential angle.
- The wear process can be divided into the steady wear stage and the severe wear stage according to the wear rate and the maximum wear depth.

# Research on wear prediction of piston/cylinder pair in axial piston pumps

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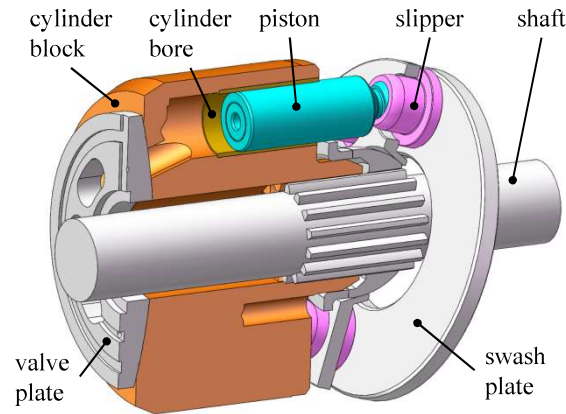
## Abstract

The piston/cylinder pair is the **critical** lubricating interface of axial piston pumps. It suffers from excessive wear, especially under high output pressure. The performance degradation of the piston/cylinder pair is significant to be clarified. In this paper, a wear prediction method of the piston/cylinder pair is established by coupling the load-bearing and lubrication parameters calculation model and the wear calculation model. **The models are validated through experiments. The experimental and simulated results show** that the wear of two ends of the cylinder bore is **severe** in the specific ranges of circumferential angle. The time-varying wear process of the piston/cylinder pair **can be** obtained by using this method; **therefore, the maintenance time can be predicted.**

Keywords: piston/cylinder pair, wear prediction, load-bearing and lubrication parameters, axial piston pump

## 1. Introduction

Axial piston pumps **are** important power **components** in **hydraulic** fluid power systems, **which are** widely applied in aerospace, industrial and mobile machinery for its high-power density [1]. **Fig. 1** shows the general configuration of the axial piston pump which is comprised of a valve plate, a cylinder block, several pistons and slippers, a swash plate, and a shaft. Axial piston pump can be defined as a positive displacement pump, **in which the hydraulic fluid** is sucked and discharged through the change of the piston chamber volumes [2]. The piston is connected with the slipper which clings on the inclined swash-plate. When the pump **operates**, the cylinder block is driven by the shaft and rotates about **the shaft**. The pistons and the slippers rotate about the shaft with the cylinder block. Due to the slipper and the inclined swash plate, the pistons reciprocate within the cylinder bore, and the piston chamber volumes change. The friction pair between the piston and the cylinder bore is called piston/cylinder pair.



**Fig. 1:** General configuration of axial piston pump

It is urgent for piston pumps to be more compact and lightweight to meet the increasingly stringent requirements of different applications. One of the most effective methods to enhance the power/weight ratio is enhancing the working pressure. However, the force condition of the piston/cylinder pair is extremely severe under high working pressure, and the possibility of excessive wear significantly increases [3, 4]. As one of the critical friction pairs of axial piston pump, the excessive wear of the piston/cylinder pair could deteriorate the oil suction and discharging and lead to the failure of the pump. In order to react in due time and avoid unplanned machine breakdown, it is important to clarify the wear process of piston/cylinder pair. The oil film between the clearance of friction pairs of axial piston pump has a function of lubricating and sealing. The distribution characteristics of oil film, such as pressure and thickness, directly reflect the load-bearing and lubrication condition of the sliding surface, which determines whether the piston/cylinder pair is under dry friction, boundary friction or fluid friction [5]. Moreover, the surface micromorphology of piston/cylinder pair changes along with the wear process, which causes the oil film characteristics to change accordingly. Therefore, there is a strong interaction between the oil film characteristics and wear of the piston/cylinder pair.

Researchers are conducting the investigations on the oil film characteristics investigation of the axial piston pumps. Kolk [6] firstly obtained the pressure distribution of the oil film between the piston/cylinder pair by solving Reynold Equation, but the piston/cylinder pair was simplified to a sloping plain bearing with a load on the side edge which is quite different from the actual situation. More realistic force analysis was considered by Fang and Shirakashi [7], and they numerically calculated the thickness field of the oil film between the piston/cylinder pair. Furthermore, Ivantysynova, et al. [8-10] considered the non-isothermal flow conditions based on the energy equation, and a complete numerical simulation model of oil film characteristics calculation has been developed. There are several theoretical analysis platforms of friction pair oil film for axial piston pumps such as CASPAR [11], PUMA [12-15] and ViSPA [16], which are useful and valuable for the design and optimization of friction pairs of axial piston pump. However, it is noticed that the effect of wear on the oil film bearing surface is not considered in these theoretical models. Therefore, the capability of analysing the change of oil film characteristics with a long operating time is limited.



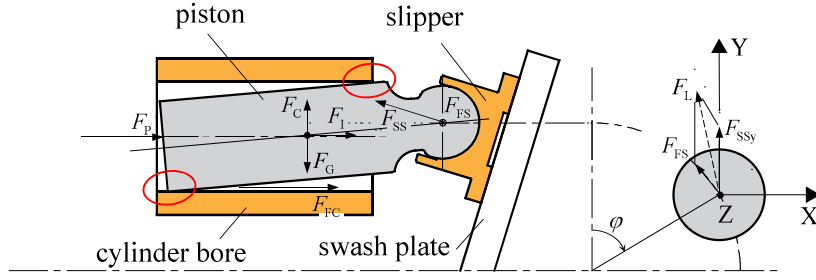
Many fundamental wear theories have been proposed [17-19] and are widely used in wear analysis of combustion engine, plain bearing, railway wheel-rail. Mayer and Ting [20] established a wear analysis model of the piston ring/cylinder liner system based on Archard wear model. Nautiyal [21] conducted experimental investigations to verify the simulated wear conditions between the piston ring and cylinder liner. For further calculation process, Bartel, et al. [22] introduced a computational model for calculating transient wear characteristics of plain bearings, and the modifications to the rough surfaces resulting from the running-in process are taken into consideration. Comparing with the piston ring/cylinder liner of the engine and the plain bearing, longer axial length of friction surface of the piston/cylinder pair could result in more complicated force condition of the piston. There is few research on the wear process of friction pairs in the field of the axial piston pump. Ma et al [23] presented an approach to analyze the wear behavior of swash plate/slipper pair considering the temperature, the outlet pressure and the rotational speed. But the wear process with an operating time cannot be clarified by using this method which neglects the distribution characteristics of oil film.

In this paper, a wear prediction method that considers the interaction between load-bearing and lubrication parameters and surface wear of piston/cylinder friction pair is proposed. Using this method, the time-varying wear profile of the entire cylinder bore can be achieved and analyzed. The accelerated lifetime investigation on an axial piston pump was conducted, and the wear profile of piston/cylinder pair was measured to determine the wear coefficient and verify the simulated results. The paper is outlined as follows: the simulation model is proposed and explained in detail in Section 2; Section 3 presents the establishment of the test rig and experimental results; Validation of the simulation models is conducted through real-time experiments. A comprehensive discussion is given in Section 4, followed by the conclusions in Section 5.

## 2. New Analytical Models

### 2.1. Dynamic analysis of piston/cylinder pair

The main external forces applied on the piston are shown in Fig. 2. The supporting force of the swash plate  $F_{SS}$  and the pressure force  $F_p$  enable the piston to reciprocate in the cylinder bore.  $F_{SSy}$  is the lateral component of  $F_{SS}$ . The friction force of slipper  $F_{FS}$  is generated by the sliding of slipper on the swash plate. The resultant force of  $F_{SSy}$  and  $F_{FS}$  is  $F_L$ .  $F_{FC}$  is the friction force between the cylinder and the piston,  $F_C$  is the centrifugal force of the piston,  $F_I$  is the inertia force of the piston.  $F_G$  is the gravity of the piston.



**Fig. 2:** External forces applied on the piston

The tiny clearance between the piston/cylinder pair and the large lateral force  $F_L$  cause the tilt of the piston in the cylinder bore. The squeezing effect of the oil film will be generated by the radial motion, and the dynamic pressure effect of wedge-shaped oil film will be generated with the motion of the piston. As indicated in the red circle in **Fig. 2**, the solid contact pressure will be formed if the thickness of oil film at that position is very tiny. The reaction force which is in balance with the external forces is produced by the squeezing effect, the dynamic pressure effect and the solid contact pressure. The force and moment equilibrium equations of the piston are given as:

$$\begin{cases} F_X = F_{\text{ext}X} + F_{\text{oil}X} + F_{\text{con}X} = 0 \\ F_Y = F_{\text{ext}Y} + F_{\text{oil}Y} + F_{\text{con}Y} = 0 \\ M_X = M_{\text{ext}X} + M_{\text{oil}X} + M_{\text{con}X} = 0 \\ M_Y = M_{\text{ext}Y} + M_{\text{oil}Y} + M_{\text{con}Y} = 0 \end{cases} \quad (1)$$

where  $F_{\text{ext}X}$ ,  $F_{\text{ext}Y}$ ,  $M_{\text{ext}X}$  and  $M_{\text{ext}Y}$  are the external forces and moments,  $F_{\text{oil}X}$ ,  $F_{\text{oil}Y}$ ,  $M_{\text{oil}X}$  and  $M_{\text{oil}Y}$  are the reaction forces and moments generated by the hydrodynamic pressure of the oil film,  $F_{\text{con}X}$ ,  $F_{\text{con}Y}$ ,  $M_{\text{con}X}$  and  $M_{\text{con}Y}$  are the reaction forces and moments generated by the solid contact pressure of the piston and the cylinder bore,  $F_X$ ,  $F_Y$ ,  $M_X$  and  $M_Y$  are the resultant forces and moments in X and Y directions, respectively.

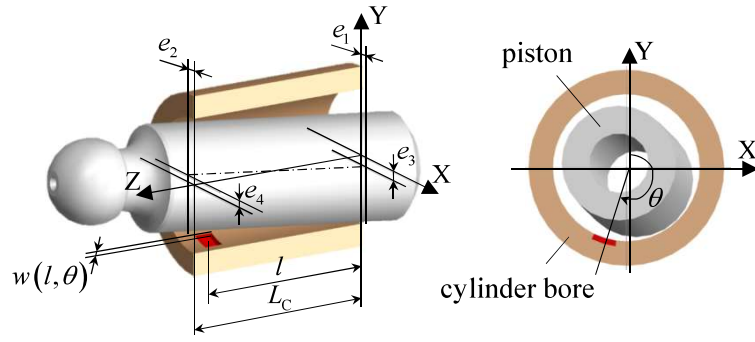
$F_{\text{oil}}$  and  $F_{\text{con}}$  reflect the load-bearing condition of the piston/cylinder pair. Therefore, the hydrodynamic pressure of the oil film  $p$  and the solid contact pressure of the piston and cylinder bore  $p_s$  can be defined as the load-bearing parameters of the piston/cylinder pair. The oil film thickness is defined as the thickness of the lubricating film between the piston/cylinder pair. The load-bearing and lubrication parameters (LBLPs) of the piston/cylinder pair consist of the hydrodynamic pressure  $p$ , the solid contact pressure  $p_s$  and the oil film thickness  $h$ . LBLPs are scattered and different in the entire oil film field, and they need to be solved to determine the lubricating condition and wear process.

## 2.2. Calculation of LBLPs

A numerical model is created to calculate the distributive LBLPs of the piston/cylinder pair.

The oil film thickness between the piston/cylinder pair is related to the posture of the piston in the cylinder bore. When the surface wear occurs, the wear depth  $w(l, \theta)$  must be considered to achieve

more accurate oil film thickness. **Fig. 3** shows the titling state of the piston in the cylinder bore exaggeratedly.



**Fig. 3: Titling state of the piston**

The posture of the piston can be represented by the eccentricities of two sections relative to the cylinder bore. The oil film thickness can be defined as the clearance between the piston and the cylinder bore in the radial direction, and it is given by:

$$h(l, \theta) = (D_c - D_p) / 2 + w(l, \theta) - [e_1 - (e_1 - e_2) l / L_c] \cos(\theta) - [e_3 - (e_3 - e_4) l / L_c] \sin(\theta) \quad (2)$$

where  $e_1$  and  $e_2$  are the eccentricities in the X direction of the two sections, respectively.  $e_3$  and  $e_4$  are the eccentricities in the Y direction of the two sections, respectively.  $L_c$  is the length of the cylinder bore,  $D_c$  is the diameter of the cylinder bore, and  $D_p$  is the diameter of the piston.

The elastic deformation could occur on the piston and the cylinder bore when their surfaces contact. There are rough peaks on the surface of piston and cylinder bore. Therefore, a minimum contact oil film thickness  $h_m$  can be determined by the surface roughness of the friction pair is set to estimate whether the contact occurs. The cross-section of the piston/cylinder pair in the case of critical contact is shown in **Fig. 4(b)**. The definition of  $h_m$  [24] is shown as:

$$h_m = 3\sqrt{R_{qp}^2 + R_{qc}^2} \quad (3)$$

where  $R_{qp}$  and  $R_{qc}$  are the root mean square (RMS) roughness of the piston and the cylinder bore respectively.

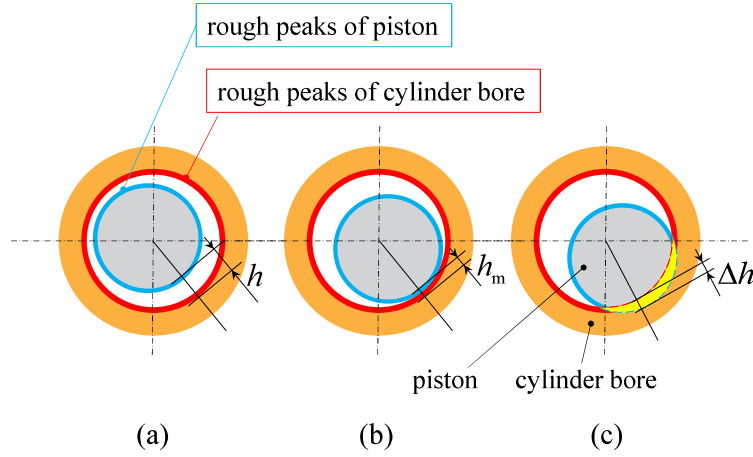
Both the piston and the cylinder bore are considered to be elastic. The elastic deformation occurs when the oil film thickness is thinner than  $h_m$ . The elastic deformation  $\Delta h$  is shown in **Fig. 4(c)** and can be calculated as using Eq. 4:

$$\Delta h = \begin{cases} 0 & h(l, \theta) \geq h_m \\ h_m - h(l, \theta) & h(l, \theta) < h_m \end{cases} \quad (4)$$

It can be seen that  $\Delta h$  is the result of the elastic deformation of the piston and that of the cylinder bore. The solid contact pressure  $p_s$  generated by the elastic deformation of the piston and the cylinder bore can be solved using Eq. 5[25]:

$$\Delta h = p_s D_p / E_p + p_s H_c / E_c \quad (5)$$

where  $E_p$  and  $E_c$  are the elasticity modulus of the piston and the cylinder bore respectively,  $D_p$  is the diameter of the piston,  $H_c$  is the thickness of the cylinder block in the radial direction.

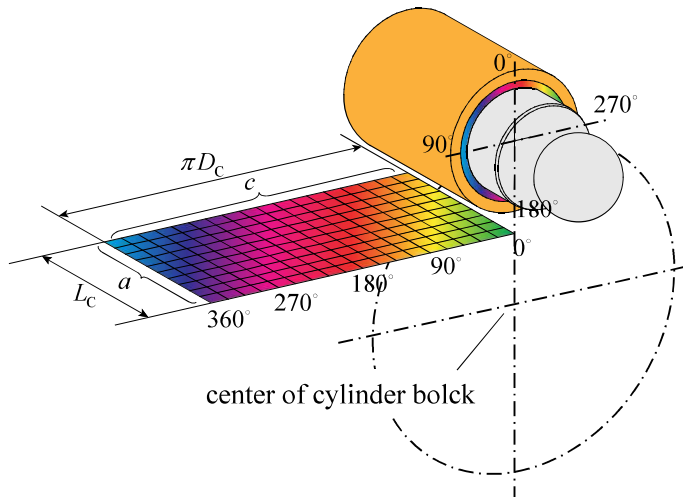


**Fig. 4:** Cross-section of the piston/cylinder pair in different cases

The hydrodynamic pressure of the oil film  $p$  can be represented by using Reynold Equation as shown in Eq. 6:

$$\frac{\partial}{\partial x} \left( \frac{\partial p}{\partial x} \frac{h^3}{\mu} \right) + \frac{\partial}{\partial z} \left( \frac{\partial p}{\partial z} \frac{h^3}{\mu} \right) = \alpha \omega_p \frac{D_c}{2} \frac{\partial h}{\partial x} + u \frac{\partial h}{\partial z} + 2 \frac{\partial h}{\partial t} \quad (6)$$

where  $\mu$  is the viscosity of the oil, and  $\omega_p$  is the spinning speed of piston,  $u$  is the sliding velocity of the piston surface. For the stability of calculation, the oil film thickness  $h$  is regarded as  $h_m$  when the calculated result of Eq. 2 is less than  $h_m$ . In Eq. 6, the first two items on the right side of the equation represent the dynamic pressure effect of the wedge-shaped oil film pair, and the third item represents the squeezing effect of oil film caused by the micro-radial motion of the piston. It is difficult to solve Eq. 6 because it is a partial differential equation with the diffusion term and the source term. Therefore, the finite volume method is used to discretize the oil film and the Cyclic Tridiagonal Matrix Algorithm (CTDMA) is applied to solve the oil film pressure field of the piston/cylinder pair. The pressure field is divided into  $a \times c$  grids and can be expanded to a plane for intuitive as shown in Fig. 5. In the contrast to the pressure field, the grid area of oil film thickness field is a quarter of the pressure field to avoid false diffusion.



**Fig. 5:** Divided oil film of piston/cylinder pair

An initial oil film thickness field and corresponding thickness changing rates are assigned in Eq. 6. The pressure distribution of piston/cylinder pair oil film can be achieved by solving the discretized Reynolds Equation in order to determine the oil film reaction force on the piston. Then, the Newton-Raphson method is used for the iterative solution of the piston force balance equation. The oil film thickness and the thickness varying rate will be adjusted automatically until the deviation of force balance is less than a given threshold. Empirically, the calculated LBLPs of one revolution show cyclicity after four computing cycles, which indicates that the calculation is converged and then the calculated result of the last revolution is output.

Fig. 6 shows the calculation process of the LBLPs. In Fig. 6,  $k$  is the rotated angle of the cylinder with the resolution of 1 degree. The simulated results show periodicity after about 3 cycles (360 degrees per cycle) of simulation according to the experience of using this simulation model. Therefore, when the number of simulation cycles is equal to or greater than 4, the simulation is considered to converge and the results of LBLPs are output.  $\Delta \dot{e}$  is the variation of  $\dot{e}$  in each iteration, and it varies automatically using the Newton-Raphson method.  $F_b$  is the threshold of the force balance deviation which equals 0.1N. The Newton-Raphson method for solving nonlinear equations is completed when the converge condition  $\|f(\dot{e}_k)\| \leq F_b$  is satisfied. The wear profile of the entire cylinder bore  $w$  is obtained by using the wear calculation model introduced in the following section, and the discretized oil film thickness  $h$  is determined by wear depth  $w$  and the posture of the piston  $e$ .

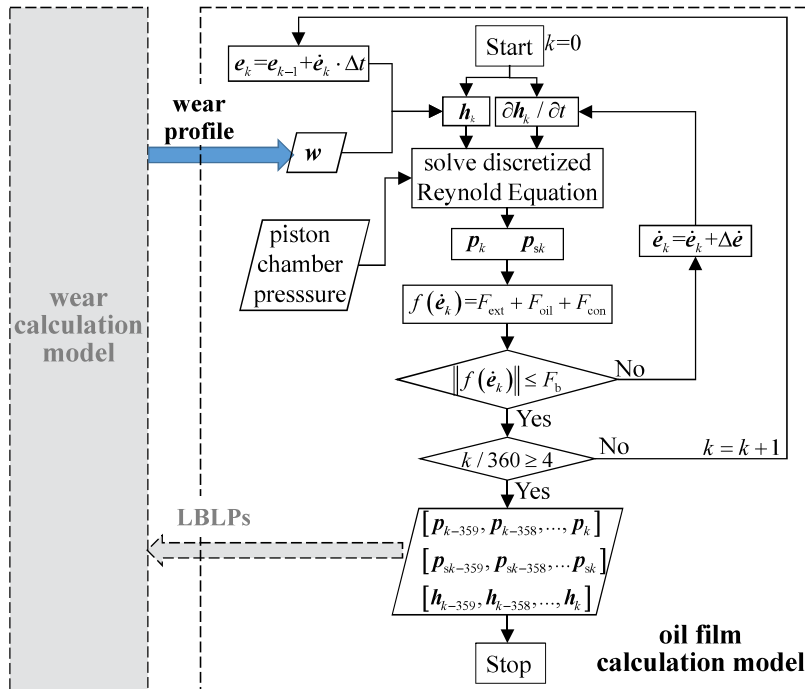
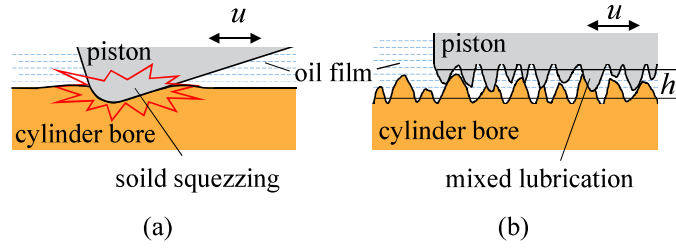


Fig. 6: Schematic diagram of LBLPs calculation

### 2.3. Influence of LBLPs on wear calculation

The LBLPs determine the load-bearing and lubrication conditions of the piston/cylinder pair.



**Fig. 7:** Load-bearing and lubrication conditions of piston/cylinder pair

As shown in **Fig. 7(a)**, the external force is too large for the oil film to provide enough reaction force to balance it. The piston and the cylinder squeeze and slide against each other. The oil film is broken when the solid contact pressure is very large. In this case, the oil film thickness  $h$  calculated by Eq. 2 can be negative. In order to represent the actual situation, the oil film thickness is considered as zero.

As shown in **Fig. 7(b)**, the roughness peaks of the piston surface contact with the cylinder bore. In this case, the oil film is not broken yet, and the solid contact pressure is small. The roughness peaks of the piston are visco-elastic. When the roughness peaks slide against the cylinder bore, it could take time for them to deform. If the acting time is less than the deforming time, the roughness peaks cannot deform thoroughly, and they will run into the cylinder bore [26]. When the thickness of the oil film is thinner than  $h_t$  which represents the height of the rough peak after viscoelastic deformation, it is considered that this is a mixed lubrication condition that could give rise to sliding wear. The expression of  $h_t$  is shown in:

$$h_t = \delta_0 / e^{\Delta/2u\tau} \quad (7)$$

where  $\delta_0$  is the height of roughness peak,  $\Delta$  is the wavelength of roughness peak,  $\tau$  is the delay time of the piston material. The  $h_t$  is the height of the rough peak after viscoelastic deformation which is lower than the  $h_m$ . When the calculated oil film thickness is thinner than  $h_m$ , the contact of roughness peaks contributes to the load-bearing of friction pairs. However, the lubricating condition is still oil lubrication as long as the oil film thickness is larger than  $h_t$ .

The wear does not occur when the thickness of the oil film thickness is higher than  $h_t$ .

We defined the case in **Fig. 7(a)** as condition (a) and the case in **Fig. 7(b)** as condition (b), and the load-bearing and lubrication conditions can be judged as:

$$\begin{cases} h = 0 & \text{condition (a)} \\ 0 < h \leq h_t & \text{condition (b)} \end{cases} \quad (8)$$

The wear mechanisms are multifarious under different load-bearing and lubrication conditions. The adhesive nodes will increase when the solid squeezing occurs as shown in **Fig. 7(a)**. And the adhesive nodes may lead to shearing fracture and surface abrasion. The wear depth  $w$  can be calculated by using the adhesive wear model as shown in Eq. 9[17]:



$$dw = k_s \frac{p_s}{3\sigma_s} ds \quad (9)$$

where  $s$  is the sliding distance,  $\sigma_s$  is the compressive yield limit which is related to the rigidity of the worn material,  $k_s$  is the wear coefficient which is always determined by experiments. The material of the piston is steel, and it is copper for cylinder bore in general. The worn surface is cylinder bore which is much softer than the piston, in accordance with the actual wear situation of the commercial axial piston pump.

As shown in Fig. 7(b), the oil film pressure is insufficient to form the adhesive nodes. However, the sliding wear will occur when the height of the roughness peak after viscoelastic deformation is higher than the oil film thickness. The wear depth of the cylinder bore can be calculated by the partial-EHL contacts sliding wear model as shown in Eq. 10[26]:

$$dw = \frac{u dt}{dA} \left[ \delta_0 e^{-\Delta/2u\tau} - h \right]^2 \frac{\Delta}{\delta_0} \quad (10)$$

where  $t$  is the sliding time, and  $A$  is the wear area which is equal to the grid area of oil film thickness field. The LBLPs are the significant parameters of the wear calculation methods. As for the adhesive wear, the load on the worn surface is presented by the solid contact pressure  $p_s$ . For partial-EHL contacts sliding wear, the comparison of oil film thickness  $h$  and the roughness peak height is very important.

The wear calculation model is shown in Fig. 8. The LBLPs are discretized into each grid to judge the wear mechanism and used to calculate the wear depth. The wear depth of each grid  $dw$  is synthesized into the wear profile of the entire cylinder bore  $w$ . The surface profile of the piston/cylinder pair will change after the wear occurs, which affects the calculation of LBLPs, and the LBLPs also influence the calculation of wear process.

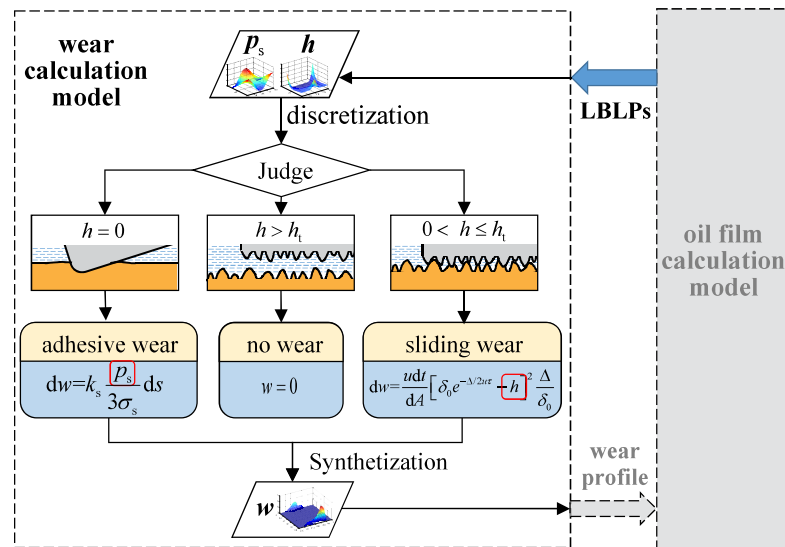


Fig. 8: Schematic diagram of the wear calculation model

## 2.4. Process of the wear prediction method

The interaction between the surface wear and the LBLPs has been clarified in section 2.3. However, the wear depth caused by one revolution of the pump is insufficient to impact the LBLPs and it is time-consuming to recalculate the oil film after each revolution. Therefore, a wear depth threshold  $w_t$  is set to determine whether the oil film needs to be recalculated. The wear profile of one revolution is superimposed on the previous wear until the threshold value  $w_t$  is exceeded and then the oil film is recalculated.

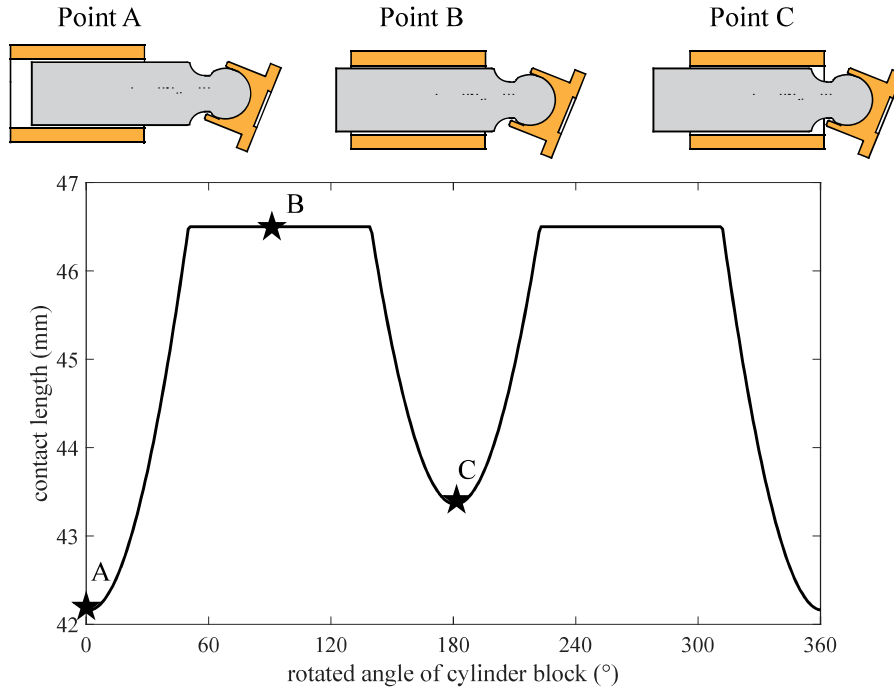
In the wear prediction method, the structural parameters, material parameters, working conditions and parameters in simulations are listed in Table 1.

Table 1 Parameters using for the wear prediction method

Parameters	Values	
Diameter of cylinder bore	28	[mm]
Length of cylinder bore	46.5	[mm]
Axial length of piston surface	64.1	[mm]
Angle of swash plate	15	[°]
Brinell hardness of cylinder bore	270	[MPa]
Elastic modulus of cylinder bore	106	[GPa]
Elastic modulus of piston	206	[GPa]
$\delta_0$ of piston surface	0.7735	[ $\mu\text{m}$ ]
$\Delta$ of the piston surface	35.2	[ $\mu\text{m}$ ]
Pressure in pump shell	0.5	[MPa]
Outlet pressure	43	[MPa]
Rotational speed	1450	[rpm]
Number of pressure field grids in the circumferential direction	17	[-]
Number of pressure field grids in the axial direction	44	[-]
Force balance deviation	0.1	[N]
Number of simulation cycles of LBLPs calculation	4	[-]

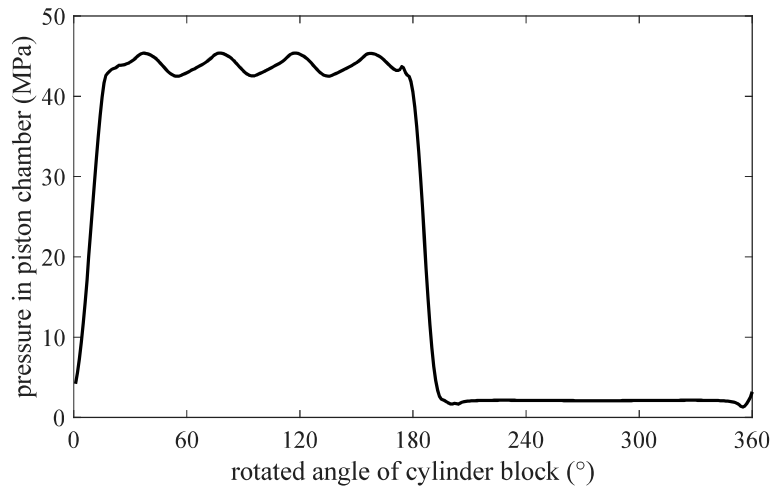
The contact length of the piston and the cylinder bore vary with the rotating cylinder. The curve of the contact length and corresponding contact states is plotted based on the structure of the simulated pump, as shown in Fig. 9.





**Fig. 9:** Contact length of piston and cylinder bore

The pressure in the piston chamber is a **crucial** boundary condition that needs to be obtained by Computational Fluid Dynamics (CFD) **model**. It is related to the working condition of the pump like inlet and outlet pressure. **and** determines the pressure force  $F_p$ , **as** shown in **Fig. 2**. The simulation model of the axial piston pump is **created based on a** commercial CFD **platform**. The result of the piston chamber pressure **is** shown in **Fig. 10**.



**Fig. 10:** Simulated result of piston chamber pressure

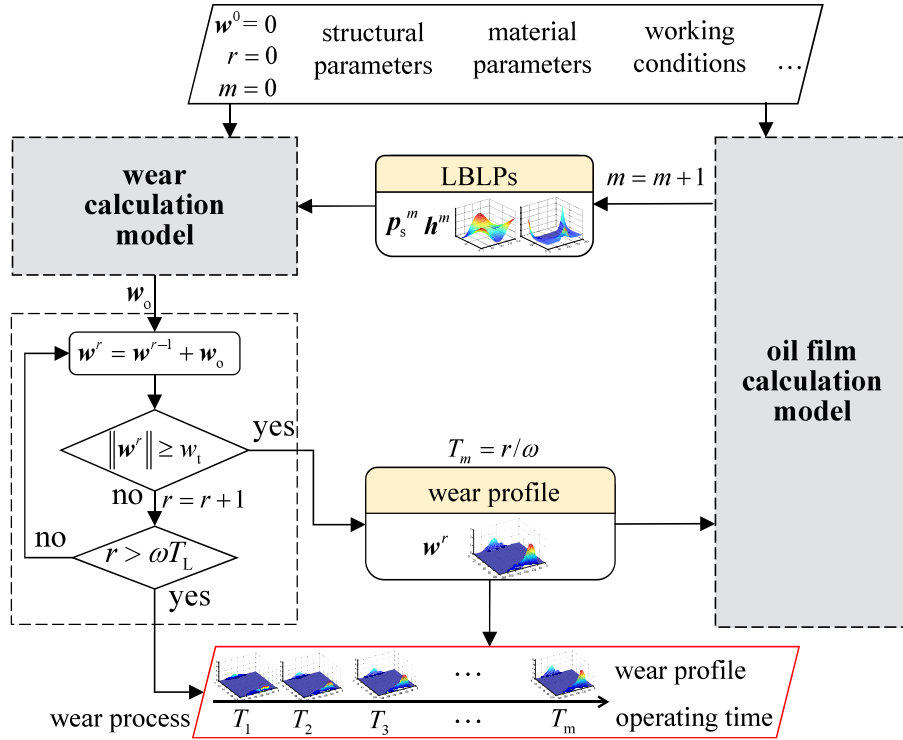
The **time-varying** wear process of the cylinder bore in certain working conditions can be obtained by the following process.

1. **The** LBLPs are calculated by the oil film calculation model.
2. **The** LBLPs are **fed** into the wear model **as the inputs** to **obtain** the wear profile of one revolution.
3. As described earlier in section 2.4, in order to **make the calculation more efficient**, the wear profile is superimposed linearly with the number of revolutions until the wear depth exceeds the threshold  $w_t$ .

4. When the threshold is exceeded, the wear profile will be input to the oil film model to recalculate the LBLPs. At the same time, the wear profile is updated as the outputs. The corresponding operating time can be calculated by the revolutions of the pump and the rotational speed  $\omega$ .

5. The above steps are repeated until the total operating time  $T_m$  is reached.

The schematic diagram of the method is shown in **Fig. 11**.



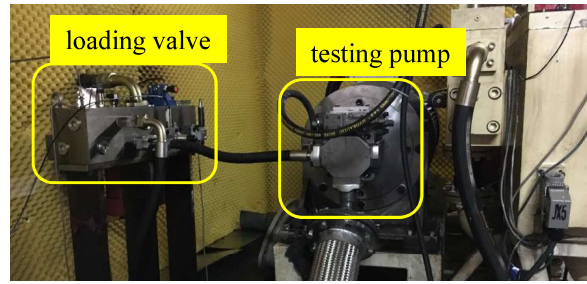
**Fig. 11:** Schematic diagram of the wear prediction method

In **Fig. 11**,  $r$  is the revolution of the pump,  $m$  is the count of LBLPs calculation.  $w_0$  is the wear profile of the entire cylinder bore during one revolution,  $w^r$  is the wear profile of the entire cylinder bore during  $r$  revolutions,  $w^0$  is the initial wear profile.

### 3. Experimental Investigation

#### 3.1. Axial pump testing

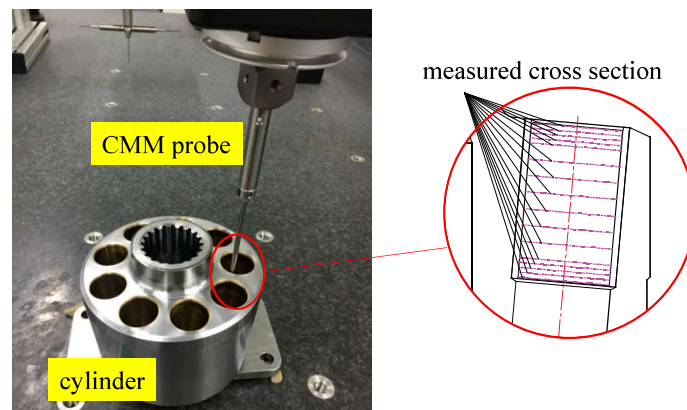
A commercial axial pump was tested to analyze the wear regions and corresponding wear depth of the cylinder bore. The test lasted for 240 hours on an accelerated lifetime testing bench. The accelerated lifetime testing condition is consistent with the simulated conditions as listed in **Table 1**. The loading pressure of the test pump for an accelerated lifetime test is 1.23 times higher compared to the normal working pressure which is 35MPa. **Fig. 12** shows the testing bench, which was built according to the Standard JB/T7043-2006 [27].



**Fig. 12:** Testing bench and the axial pump

### 3.2. Wear measurement

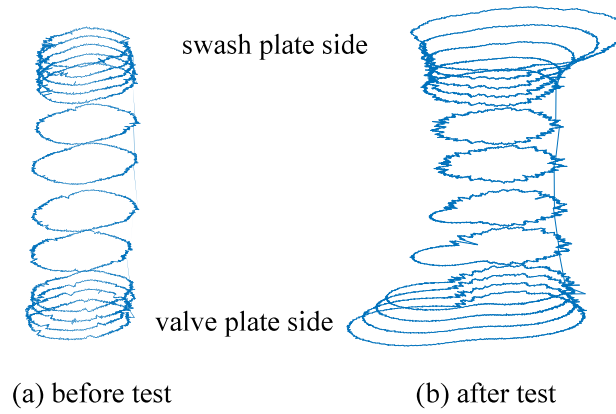
The pump was disassembled and the cylinder block was taken out before and after the accelerated lifetime test so that the wear of the cylinder bore could be measured. The coordinate measuring machine (CMM) is utilized to measure the circumferential profile of the cylinder bore in micron scale. The circumferential profile of the section on the cylinder bore is obtained after the CMM probe scans the inner wall of the cylinder bore. The resolution of the measuring equipment is smaller than  $1\mu\text{m}$ , and it is sufficient to meet the requirement of wear measurement. **Fig. 13** shows the measurement of the cylinder bore and the sites of the measured sections.



**Fig. 13:** Measurement of the cylinder bore

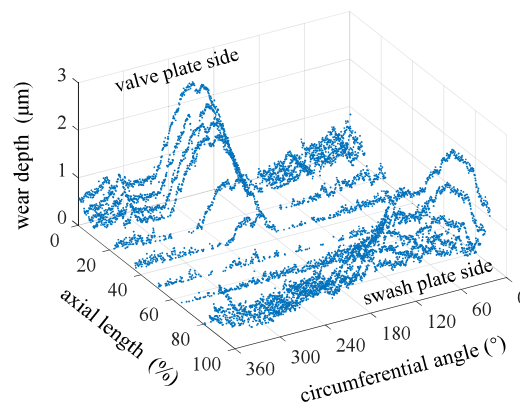
The circumferential profiles of the sections can be fitted into the three-dimensional profile of the entire cylinder bore. It can be inferred that the axial wear gradient near both ends of the cylinder is more significant than that elsewhere due to the structure of the piston/cylinder and the force condition, as shown in **Fig. 2**. This is because the measured sections near both ends of the cylinder were more intensive than that elsewhere.

The three-dimensional profiles of the cylinder bore before and after the accelerated lifetime test are shown in **Fig. 14**.



**Fig. 14:** Measured three-dimensional profile of the cylinder bore

The profile of the cylinder bore before the test is close to a regular cylinder and the shape and diameter of each section are almost the same, while the diameters of the sections near both ends are much larger after 240-hour test due to the wear process. The actual wear profile of the cylinder bore can be obtained by the difference of the cylinder bore profiles before and after the test. It can be expanded to a plane as shown in Fig. 15. It is expanded in the same way as Fig. 5. The vertical axis represents the wear depth  $w$ . The tested piston surface was measured using the same method, but no obvious wear profile was found.

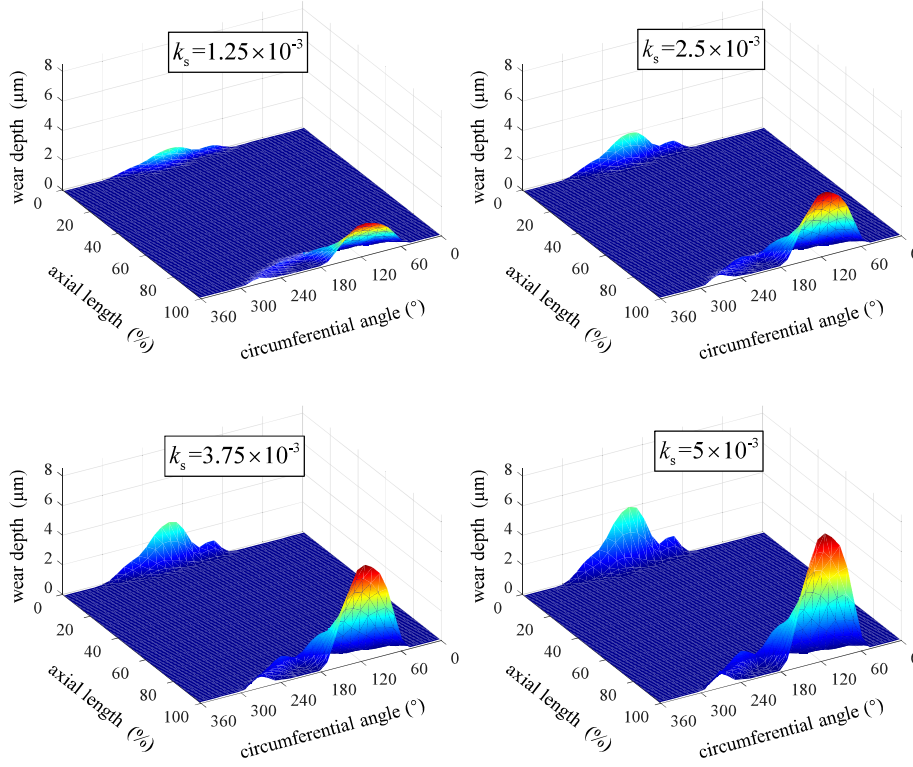


**Fig. 15:** Measured wear profile of the cylinder bore

## 4. Analysis and discussion

### 4.1. Determination of the wear coefficient

For the adhesive wear model mentioned in section 2.3,  $k_s$  is a crucial coefficient that represents the probability of adhesive nodes formation. However, the determination of  $k_s$  is quite difficult, because it varies with different load-bearing and lubrication conditions, and there are no theoretical criteria to choose it currently.



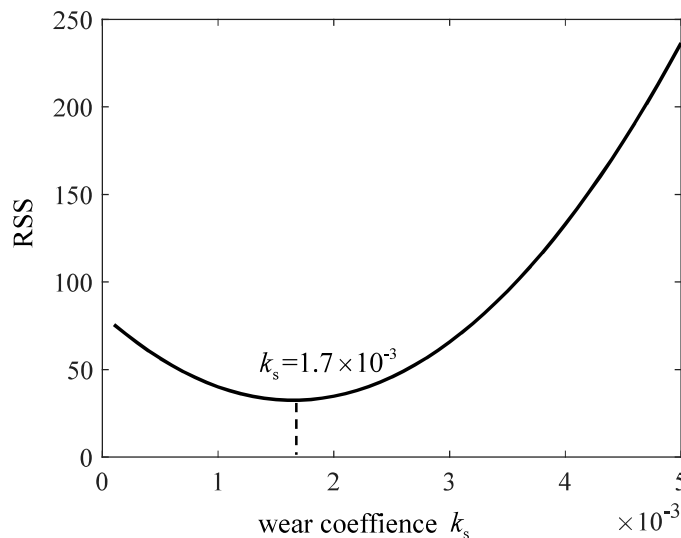
**Fig. 16:** Simulated results with different  $k_s$

**Fig. 16** shows four different simulated results with a variety of  $k_s$  ( $k_s = 1.25 \times 10^{-3}$ ,  $2.5 \times 10^{-3}$ ,  $3.75 \times 10^{-3}$  and  $5 \times 10^{-3}$ ). The  $k_s$  has little effect on where the wear is, but it has great effects on the depth of wearing. The determination of  $k_s$  is crucial for the wear calculation.

The measured result is utilized to determine the value of  $k_s$ . The discrepancy between the simulated and the measured results represent the appropriateness of the selected value of  $k_s$ . The smaller the discrepancy is, the more appropriate the  $k_s$  value is. The residual sum of squares (RSS) is widely used to measure the degree of correlation between two variables. It can be used to quantitatively describe the discrepancy between the simulated and measured results as shown in Eq. 11:

$$RSS = \sum (w_m - w_s)^2, \quad (11)$$

where  $w_m$  is the measured wear depth, and  $w_s$  is the simulated wear depth.

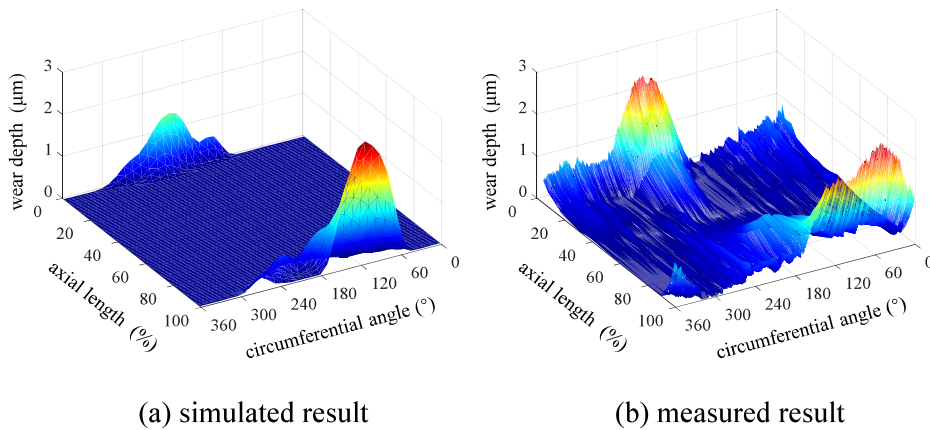


**Fig. 17:** Relationship between  $RSS$  and  $k_s$

The relationship between  $RSS$  and  $k_s$  is shown in **Fig. 17**. The simulated result reaches the best approximation to the measured result when  $RSS$  reaches the minimum value. Therefore, the value of  $k_s$  in the simulation model is set as  $1.7 \times 10^{-3}$ .

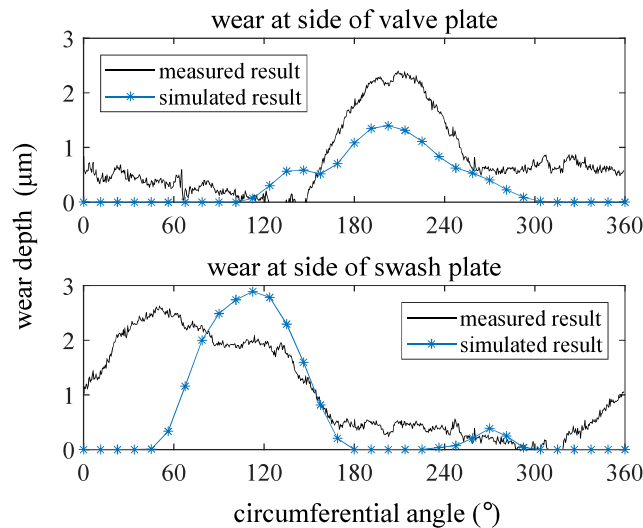
#### 4.2. Comparison between simulated and measured results

The simulated wear distribution can be obtained as shown in **Fig. 18(a)** after determining the value of the wear coefficient  $k_s$ . Both the simulated and measured results show that the most severe wear regions are near the ends of the cylinder bore. However, the circumferential angles for the two peak values are different.



**Fig. 18:** Entire wear profile of the cylinder bore

The circumferential wear profiles at both ends of the cylinder bore are shown in **Fig. 19** for a comparison.



**Fig. 19:** Circumferential profile of the cylinder bore

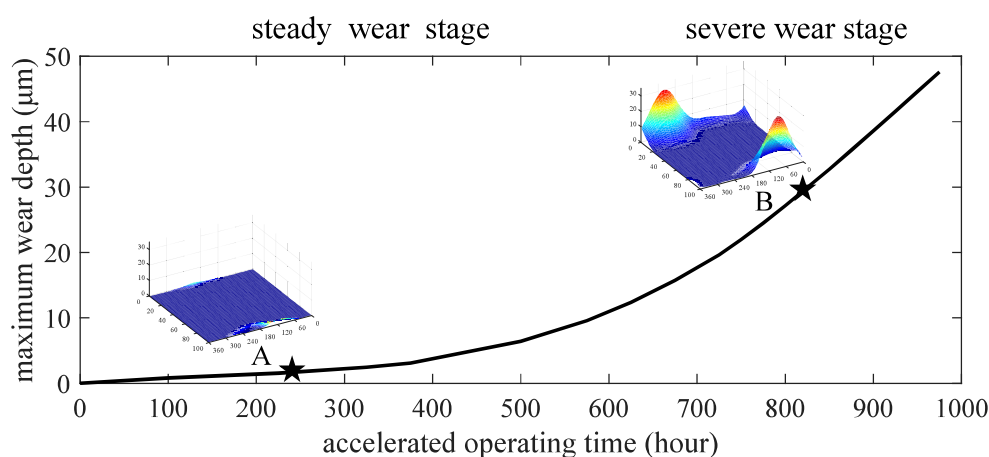
The measured result shows that there is severe wear between  $150^\circ$  and  $250^\circ$  at the side of the valve plate. And the range is  $-50^\circ$  to  $180^\circ$  for the side of swash plate. It can be seen that the simulated result is generally consistent with the measured result, but there are still some deviations. The simulation model of LBLPs is based on several hypotheses [28], which could cause the inevitable deviation of lubricating condition judgement between simulation and complicated actual state. There are



discrepancies between the wear models and the actual wear mechanism, for example, the neglect of abrasive wear due to the tiny metal particles in hydraulic oil. The accuracy of the proposed model is acceptable and can be used to investigate the relationship between the wear process and operating and structural parameters of piston/cylinder pairs, which can be very useful for analysing the failure mechanism and predicting the lifetime of axial pistons pumps.

### 4.3. Discussions

The proposed method can be used to predict the wear process of the piston/cylinder pair which is useful to pump monitoring and maintenance. Fig. 20 shows the simulated results of the wear process of the piston/cylinder pair under an accelerated lifetime testing condition. It must be acknowledged that the wear coefficient varies with actual working conditions and operating time of axial piston pumps in practice. The predicted wear process of cylinder bore under the accelerated lifetime test condition, based on the wear coefficient in Fig. 17, is only suitable for this tested axial piston pump in the discussed working conditions.

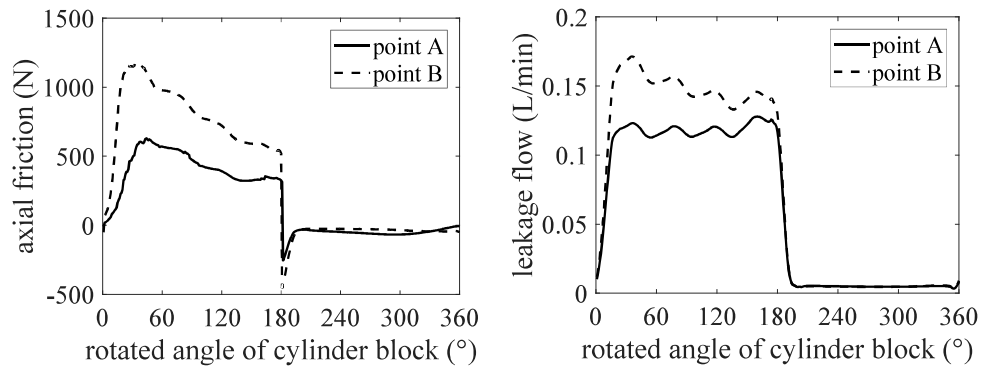


**Fig. 20:** Wear process of cylinder bore under accelerated lifetime testing condition

A typical sliding wear process can be explained with three characteristic stages, running-in wear, steady-state wear and accelerated wear according to the wear rate and the maximum wear depth [28]. In Fig. 20, the wear degree and wear rate both change with operating time, which is in accordance with the common wear mechanism.

For the 240-hour accelerated test of the pump in this paper, the wear condition of the piston/cylinder pair is at point A which is at the steady-state wear stage in Fig. 20. The point B is selected for comparison, where a rapid increase of wear rate and considerable maximum wear depth occurred, which indicates that the axial piston pump bears the risk of a sudden failure.

In addition, the axial friction and the leakage at the accelerated wear stage is worse than that at the steady-state wear stage. Fig. 21 shows the axial friction and leakage in one revolution at point A and point B, respectively, which indicates sharp reduction of efficiency of the axial piston pump.



**Fig. 21:** Axial friction and leakage at point A and point B

## 5. Conclusion and outlook

A method to predict the wear process of the piston/cylinder pair was proposed in this paper. The following conclusions can be made.

- (1) With a 240-hour accelerated test, the value of the wear coefficient is determined as  $1.7 \times 10^{-3}$ , when the discrepancy between simulated and measured results was minimized.
- (2) The simulated and measured results show that the wear of two ends of the cylinder bore is severe. The severe wear occurs in the specific ranges of circumferential angle.
- (3) The wear process of the piston/cylinder pair is useful to obtain the maintenance time of the axial piston pump.

The LBLPs calculation model is related to the working conditions of the piston pump, such as outlet pressure and rotational speed. These factors are used as accelerated variables in the accelerated life test. Through the study of this paper, the wear process under different accelerated conditions can be obtained, which is significant for the research about the accelerated life test for piston pumps.

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